

## Model and Implementation Of System Evolving Algorithm with Distributed Beginning Population

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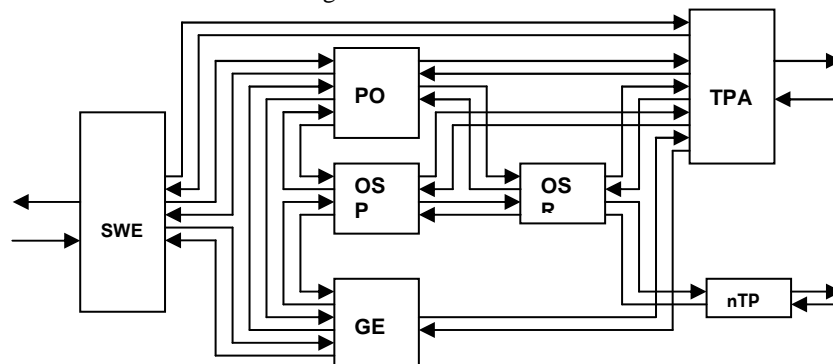
**Abstract.** This paper shows some results of using artificial intelligence methods for searching the new state of development system of electro energetic transmission network. In particular, is using evolving algorithm. Some experiments are prepared in MATLAB and Simulink environment.

**Keywords.** Artificial intelligence methods, evolving algorithm, electric power market, control theory.

### 1 Introduction

Model of Electric Power Market consists of seven subsystems, namely: Electric Power Station (SWE), Operator of Transmission System (OSP), Rotation Firm (PO), Electric Stock Exchange (GE), Operator of Distributed Systems (OSR), Receiver with TPA (TPA), Receiver without TPA (NTP)

To searching regularity of development of Power Market System is used their cybernetic model as is show on fig 1.



**Figure 1.** Cybernetic Model of Electric Power Market.  
Symbols are in the text.

One of more important systems in the structure of competition on Electric Power Market is the operator of transmission system (*Polish: Operator Systemu Przesyłowego – OSP*). OSP administer on balance market and are responsible for quality and independence of electric energy supply to the receiver and for transmission of service disbursement [1,19,29-31,33,38-41,43 ].

Although prescription of regulation of electric power action gives priority to market stability before trade actions on the market, the market generates a lot of inconvenient practice situation for regulators system, which solves shout be follows quickly to avoid the situation, which can be unprofitable or catastrophic event for electroenergetic system.

So, transmission system operator is management of transmission network, distributed of charge distribution and transmission service purchase. Besides, the action of system OSP on electric power market is regulating through condition of concession getting of Energetic Regulate Office (*Polish: Urząd Regulacji Energetyki – URE*) and normalized particularly in regulations of balance market [ ]. In Poland as OSP is acting Polish Electro-energetic Network S.A Operator. (*Polish: Polskie Sieci Elektroenergetyczne S.A. – PSE SA Operator*). A model of system OSP is shown in fig. 2, besides is taken next symbols, namely:

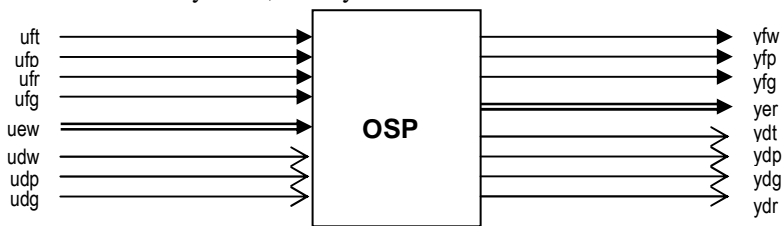


Figure 2. Model of OSP system. Symbols in the text

**(1) Describe input:**

uft – stream on title salestream of financial income on electric energy sold to TPA [thousands PLN];

ufp – stream of financial income on electric energy sold to PO [thousands PLN];

ufr – stream of financial income on electric energy sold to OSR [thousands PLN];

ufg – stream of financial income on electric energy sold to GE [thousands PLN];

uew – stream of electric energy physically transmitted from SWE to another system [GWh];

udw – decision stream concerning purchase of electric energy from SWE through TPA [GWh];

udp – stream of decision making of purchase electric energy from PO through TPA [GWh];

**(2) Describe output:**

yfw – stream of financial cost of purchase electric energy from SWE [thousands PLN];

yfp – stream of financial cost of purchase electric energy from PO [thousands PLN];

yfg – stream of financial cost of purchase electric energy from GE [thousands PLN];

yer – stream of electric energy of physic transmission from OSP to OSR [GWh];

ydt – stream of decision making of sale electric energy from OSP to TPA [GWh];

ydp – stream of decision making of sale electric energy from OSP to PO [GWh];

ydg – stream of decision making of sale electric energy from OSP to GE [GWh];

ydr – stream of decision making of sale electric energy from OSP to OSR [GWh];

(3) subsystems:

OSP – operator of transmission subsystem (Polish: operator systemu przesyłowego);

SWE – subsystem of energy generate (Polish: system wytwarzania energii)

PO – subsystem of manufacture trade;

TPA – manufacture, which action of rule TPA,

GE – energy stock-exchange;

OSR – operator of distribute subsystem.

### **(3) Describe subsystems:**

OSP – operator of transmission subsystem (Polish: operator systemu przesyłowego);

SWE – subsystem of energy generate (Polish: system wytwarzania energii);

PO – subsystem of manufacture trade;

TPA – manufacture, which action of rule TPA;

GE – energy stock-exchange;

OSR – operator of distribute subsystem.

Goal of identification of OSP is searching dependences between object characteristics in settlement state or in time during being transitory process. And next on this base can be possible say about identification responsible static's characteristics or event dynamics properties [5,9,12,37].

Of this understanding of process is to short, and particularly when it is desirable to build object model with mechanism of development. In this case identification will be leading in long time with parametric and structure changing. System OSP for which is searching dependence between input and output streams are called identification object. So, for object from figure 1 system of transmission network action as object of identification, and streams input and output are responsible constructed as vectors of measurement data, and in this practice situation there are statistics data, which are taken from annals named as Statistic of Polish Electro-Energetic (Polish: *Statystyka Elektroenergetyki Polskiej*) [36].

Goal of such defined identification as above is chose the best model from class of models or appoint such vector of parameters in order that quality function receive minimal value. Dependence parameters vectors from measurement result is named identification algorithm.

## 2 Identification of OSP

Between a lot of problems in search model of Electric Power Market [19,29-3138-41] one of most important belong problems identification power market, in this identification of development of electro-energetic transmission network (ESP). Gaining model of development system of electric power market is one of more difficult task and don't to end precise, therefore to look such models leading identification market system and their subsystems. Besides of this identification of transmission system operator is possible to mark out control subsystem and executive subsystem, in this technology subsystem such as electro energetic transmission network (ESP).

### 2.1 Chose data for identification

For leading identification of ESP system choose responsible statistic data such as length of electro energetic line, number of electro energetic stations, numbers of networks transformer, electric energy stream getting to network from responsible power stations, etc. Examples of input data is placed in works [33,38-41].

System Identification Toolbox is equipped in graphical interface GUI, which is very useful by using identification analyze researching ESP system. It is possible such define programmer than parameters of program functions will be possible chose through menu or icons [4,33,38-41].

Having prepared data to identification can be possible their import to Workspace and next leading identification. In this case responsible characteristics ESP systems is getting at last in such form as matrix th, transmission form tf, zero-pole form zpk, state space ss, etc.

### 2.2 Identification of ESP system using System Identification Toolbox

In GUI menu can be possible chose Import option in case imported input and output data (fig. 3) and quickly get some characteristic of system ESP, which examples is shown in table 1 and in table 2.

System which is identified consists of eight inputs and eight outputs. For experiment matrix consist of eight input vectors and for each case is create separate model arx and tf, zpk, **A,B,C,D** also.

It is possible use to next standard function, namely:

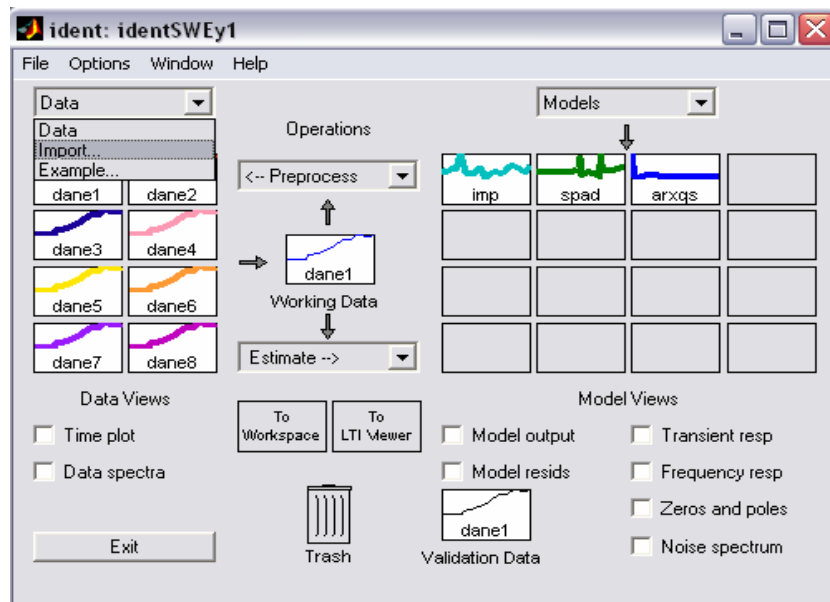
$$th = arx([y,u],[na nb nk]), \quad (2)$$

where:

y, u – column vectors (input/output),

[na, nb, nk] – coefficient of equation described the model, na – number of pole (roots in denominate), nb – number of zero (roots of nominator), nk – deleted,

th – matrix in theta format.



**Figure 3.** Graphical interface ident with examples contains characteristic of system OSP in area technology system ESP

Optimal choice of model structure is possible using iterations methods. After identification from matrix th is simple method to receive other models of systems, for example:

$$1) [l, m] = th2tf(th), \quad (3)$$

where:

m – coefficient of denominate,

l - coefficient of nominate;

$$2) zpk = zpk(th), \quad (4)$$

where:

z – zero,

p – pole;

Example of OSP model for output y1

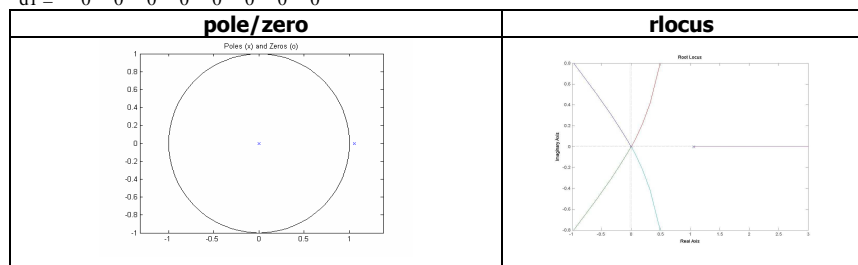
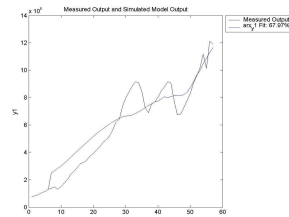
**Table 1.**

|  |   |                 |   |
|--|---|-----------------|---|
| <b>3 yfw – stream of finance expenses which is bear on purchase electric energy from SWE [thousands PLN t]</b> |   |                 |   |
| <b>4 arx</b>   |   |                 |   |
| A(q)   | 1 - 1.058 q <sup>-1</sup>                         | B5(q)           | 38.03 q <sup>-5</sup>                             |
| B1(q)  | -6.089e-014 q <sup>-5</sup>                       | B6(q)           | -72.11 q <sup>-5</sup>                            |
| B2(q)  | -6.086e-015 q <sup>-5</sup>                       | B7(q)           | 0   |
| B3(q)  | 0.1972 q <sup>-5</sup>                            | B8(q)           | 0   |
| B4(q)  | 0   |                 |   |
| <b>5 zpk</b>   |   |                 |   |
| From u1 to y1  | -6.0893e-014<br>-----<br>z <sup>4</sup> (z-1.058) | From u5 to y1   | 38.0255<br>-----<br>z <sup>4</sup> (z-1.058)      |
| From u2 to y1  | -6.086e-015<br>-----<br>z <sup>4</sup> (z-1.058)  | From u6 to y1   | -72.1062<br>-----<br>z <sup>4</sup> (z-1.058)     |
| From u3 to y1  | 0.19717<br>-----<br>z <sup>4</sup> (z-1.058)      | From u7 to y1   | 2.2204e-016<br>-----<br>z <sup>10</sup> (z-1.058) |
| From u4 to y1  | 2.2204e-016<br>-----<br>z <sup>10</sup> (z-1.058) | From u8 to y1   | 2.2204e-016<br>-----<br>z <sup>10</sup> (z-1.058) |
| <b>num/den</b>   |   | From v@y1 to y1 | 586318.2868 z                                     |
| -6.0893e-014<br>-----<br>z <sup>5</sup> - 1.0578 z <sup>4</sup>  |   |                 | (z-1.058)   |
| <b>[a,b,c,d]</b>   |   | <b>compare</b>  |   |

a1 = 1.0578 1.0000 0 0 0  
 0 0 1.0000 0 0  
 0 0 0 1.0000 0  
 0 0 0 0 1.0000  
 0 0 0 0 0

b1 = 0 0 0 0 0 0 0 0  
 0 0 0 0 0 0 0 0  
 0 0 0 0 0 0 0 0  
 0 0 0 0 0 0 0 0  
 -0.0000 -0.0000 0.1972 0 38.0255 -72.1062 0 0  
 c1 = 1 0 0 0 0

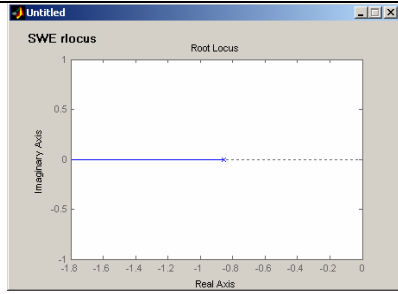
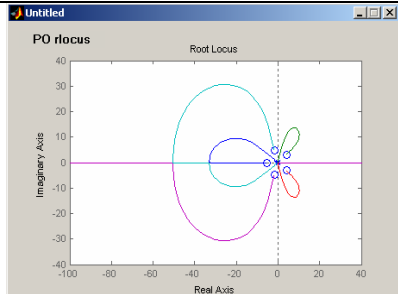
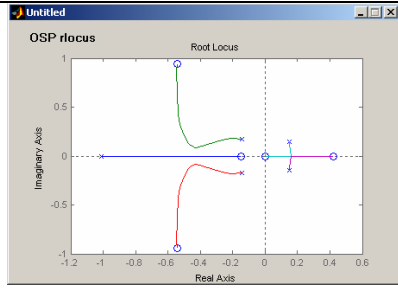
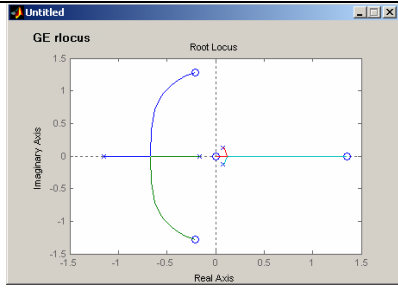
d1 = 0 0 0 0 0 0 0 0



**Table 2.** Some results of experiments of SAE action for OSP system

| Algorithm parameters    |      |                                    |     |
|-------------------------|------|------------------------------------|-----|
| Number of population    | 30   | Probability of crossover – level 1 | 0,6 |
| Number of generation    | 100  | Probability of crossover – level 2 | 0,6 |
| Probability of mutation | 0,02 | Probability of crossover – level 3 | 0,6 |

| SWE – Graph of rlocus  | PO – graph of rlocus  |
|--|---|
|   |   |
| OSP –graph of rlocus   | GE – graph of rlocus  |
|  |  |

$$3) \quad [A, B, C, D] = th2ss(th), \tag{5}$$

where:  $A, B, C, D$  – matrixes of state surface.

For presentation of results is using next functions, namely: compare ([y u], th), rlocus(l,m), pzmap(l,m). First is taken discrete model and next continue.

### 2.3 System Evolving Algorithm SAE

For generate begin population is using artificial genetic code, which is receive directly from OSP model described in transmittance form. Each chromosome can be use on tired levels. On first level genes have value as coefficient of nominate and denominate of transmission function. On second level as gene is taken al formula of nominate and denominate of transmission function. And on third level is obtained as genes separate models with single output. For selected is using modified tourney method. Is obtain a lot of result, which is published for examples in paper [33,38-41].

Example on all level is contained in table 2. SAE is implemented in language MATLAB using GUI Builder. Programmer SAE is written data from file \*.mat and next on this base is creating beginning population.

#### 2.4 Artificial Genetic code

Artificial genetic code is models code. On base of genetic code is possible search some information of system in this same way as using mathematical models [2,3,6-8,10,13,14,18,24,28,34,42]. Artificial genetic code is defined as a vector, namely:

$$K_g = [g_1, g_2, \dots, g_i, \dots, g_n), \quad (6)$$

where:  $g_i$  is  $i$  – artificial gene.

By them each of genes may be as artificial genetic code also. So it is possible obtained artificial genetic code consisted of vectors, matrixes, tales of high rows, and even in form plug one genetic code inside another.

#### 2.5 Chromosome building

Chromosome is possibility describing using three particular levels [11,15-17,20-23,25-27,35,38-41]. On high level are coefficient of nominate and denominate of discrete transmutation and as chromosome is using nominate and denominate. On the middle level as nominates and denominates is using genes. And on the lower level as genes are models of each subsystem.

For selection is using modified tourney method. Each chromosome is competitive with other, and as a winner is that which have better value of fitness function. So for adaptation flows next parameters: form of nominate, form of denominate, sign of parameters of nominate and denominate and sign of parameters of nominate and denominate.

### 3. Implementation of algorithm SAE in Matlab language

SAE application is elaboration using GUI Builder. Process consists of two steps, namely:

Step 1: generate of graphical interface of programme (\*.fig),

Step 2: implementation of SAE algorithm using Matlab languages (\*.m).

During identification of Power Market System was exported from MATLAB workspace data in transmutation form. It was next files: SWE.mat, PO.mat, OSP.mat and GE.mat.



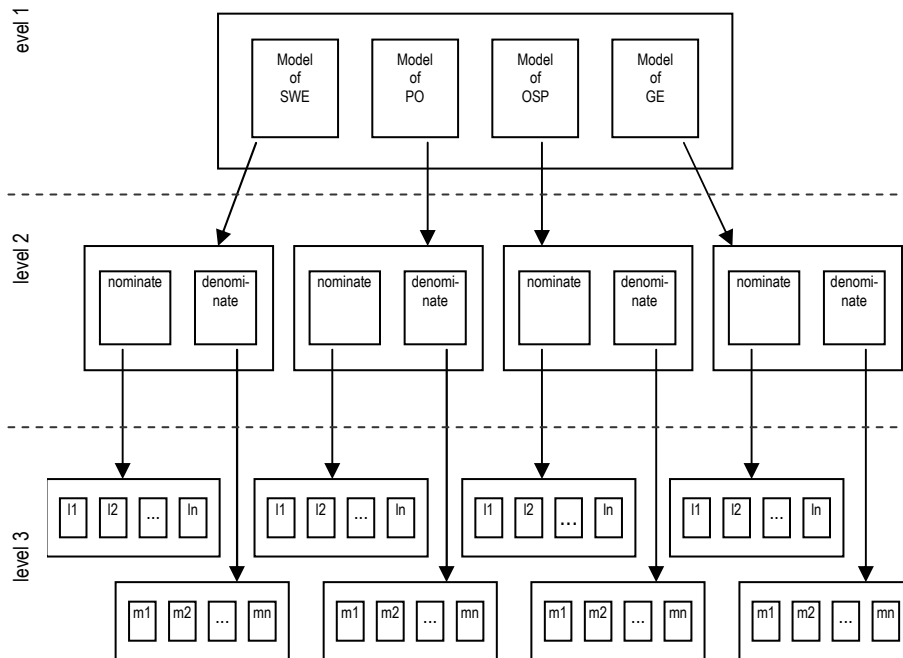


Figure 4. Scheme of chromosome building,  $i_1$  – i-nominate,  $m_i$  – i-denominate.

### 3.1. SAE Program

SAE Program is generic beginning population using \*.mat files. Next is going evaluation of chromosome, selections, crossover, mutation, etc. Condition of stopping algorithm is the reach numbers of population during working SAE algorithm. Further we have output data as a transmutation, which is presented using for example *rlocus* functions. Program is particularly described in papers [33,38-41].

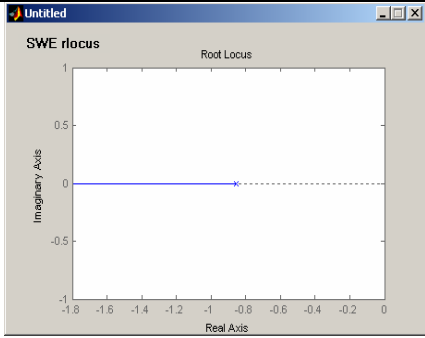
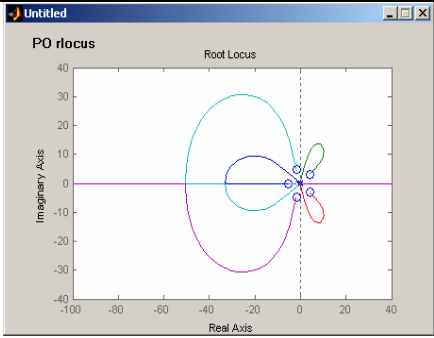
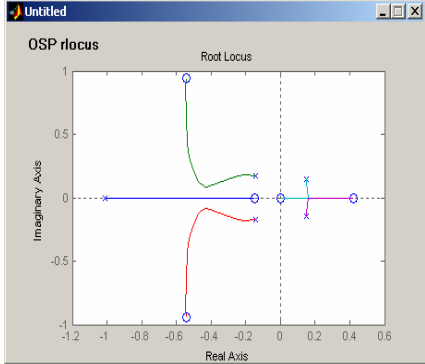
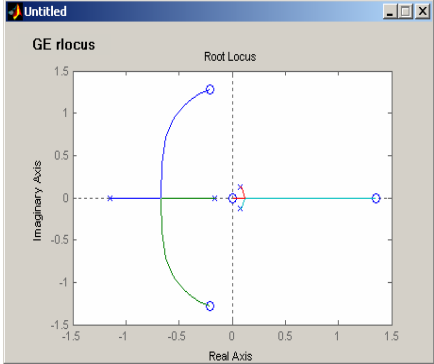
### 3.2. Examples of results

Goal of experiment is researching some results of action algorithm SAE using high probability of crossover on the all level of detail of chromosome. Some choice results is shows in table 3, and using a little probability of crossover on the all level of detail of chromosome (table 4).

**Table 3.** Experiments results 4

| Parameters of algorithm |      |                                    |     |
|-------------------------|------|------------------------------------|-----|
| Number of population    | 30   | Probability of crossover – level 1 | 0,6 |
| Number of generation    | 100  | Probability of crossover – level 2 | 0,6 |
| Probability of mutation | 0,02 | Probability of crossover – level 3 | 0,6 |

| SWE graph of rlocus  | PO graph of rlocus  |
|--|---|
|   |   |
| OSP - graph of rlocus  | GE graph of rlocus  |
|  |  |

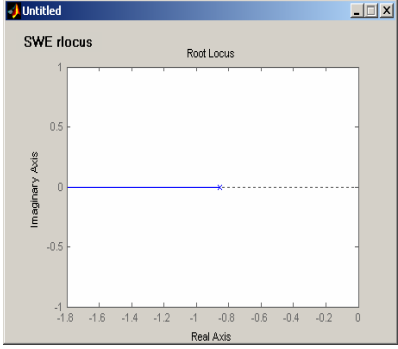
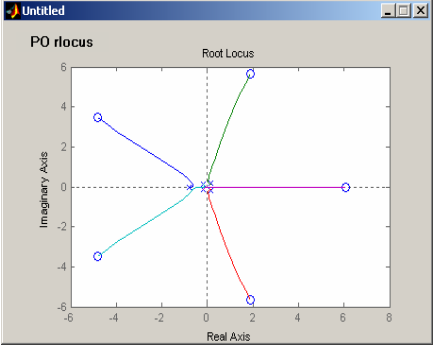
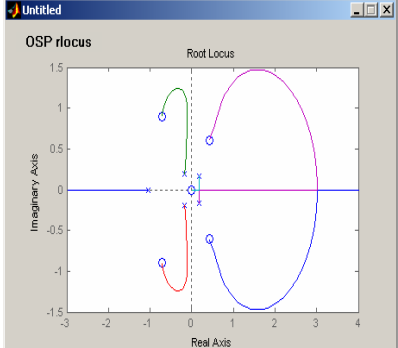
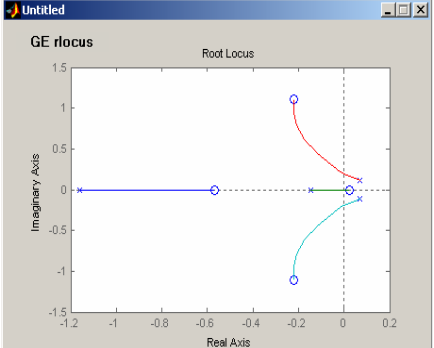
#### 4. Final remarks

Algorithm SAE is elaborated on base control theory and systems. Implementation of system evolving algorithm is prepared in MATLAB environment using such toolbox's as System Identification Toolbox, Control System Toolbox. This elaborate will be continue

Table 4. Experiments results

| Parameters of algorithm |      |                                    |     |
|-------------------------|------|------------------------------------|-----|
| Number of population    | 30   | Probability of crossover - level 1 | 0,1 |
| Number of generation    | 100  | Probability of crossover – level 2 | 0,1 |
| Pr. mutacji             | 0,01 | Probability of crossover – level 3 | 0,1 |

| SWE - graph rlocus  | PO - graph rlocus  |
|---|--|
|    |    |
| OSP - graph rlocus  | GE - graph rlocus  |
|  |  |

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